

Universidad de Granada



Mathematical Models in Neurobiology

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CIMPA 2025

La Habana, 9-20 June 2025



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Some Mathematical Models in Neurobiology

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It is now well known that neurons are the key units of the animal nervous system

In the human brain there are around 10¹² neurons

In $1mm^3$ of cortical tissue, there are about 10^5 neurons

Better understanding how the brain works is one of the great challenges of today

How can mathematics help achieve this goal?

- Mathematical models have been key to understanding how neurons work
- And they are a fundamental tool in current research

In this course we will present different models considering different scales of observation

The motivation is to collaborate as mathematicians to better understand the brain, but we also face a double mathematical challenge:

- to understand the mathematical properties of the models used by neuroscientists
- to develop new mathematical techniques that can be applied to other models

Teamwork



Structure of the course

- Neuron's biology
- Microscopic models
 - Hodgkin-Huxley model
 - Morris-Lecar model
 - FitzHugh-Nagumo model
 - Integrate-and-fire model
 - Stochastic differential equations (SDE)
- Partial differential equations (PDE)
 - Nonlinear Noisy Leaky Integrate and Fire (NNLIF)
 - Age-structured partial differential equations
- Open problems

Structure of the course

We will study

- Different scales/systems to model the behaviour of neurons populations
- Long time behaviour for some PDE models
 - Global existence versus blow-up
 - Number of equilibria
 - Stability of the equilibria
 - Entropy method
 - Discrete description for system with large transmission delay: pseudo-equilibria sequence
 - New technique using Volterra-type equation

Structure of the course

Some general references:

- Books:
 - Ermentrout & Terman, Mathematical Foundations of Neuroscience, 2010
 - Coombes & Wedgwood, Neurodynamics, 2023
- PhD Thesis:
 - Alejandro Ramos-Lora, Microscopic and mesoscopic descriptions of the Nonlinear Noisy Leaky Integrate-and-Fire model: long-time behavior and numerical simulations, 2024
 - Ricarda Schneider, Analysis and numerical simulation of network of noisy leaky integrate and fire neuron models, 2018
 - Nicolás Torres, Asymptotic behavior of solutions of the elapsed time model for neural assemblies, 2021
- **Review:** Carrillo & Roux, Nonlinear partial differential equations in neuroscience: from modelling to mathematical theory, 2025

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 - it was a continuous network of fibers
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- Camillo Golgi developed a silver nitrate staining technique (Golgi stain) that made neurons visible under the microscope. And he supported the reticular theory, which held that nerve cells formed a continuous web
- Santiago Ramón y Cajal used Golgi's technique and arrived at a different conclusion: neurons are discrete, individual cells that communicate through tiny gaps. His work led to the formulation of the neuron doctrine, which remains a cornerstone of modern neuroscience
- Golgi and Ramón y Cajal were jointly awarded the Nobel Prize in Physiology or Medicine in 1906, "in recognition of their work on the structure of the nervous system"



Drawing of the cells of the chick cerebellum by Santiago Ramón y Cajal, from "Estructura de los centros nerviosos de las aves", Madrid, 1905 (Wikimedia Commons, Public Domain)

• What is a neuron?

• Which is its function?

• How is a neuron?

	A neuron is a cell of the nervous system
CONCEPT	and is an electrically excitable cell that receives,
	processes, and transmits information
	through electrical and chemical signals

FUNCTION || It passes information on to organism

PARTS Body, Axon and Dendrite



Numerous neurons of the cerebral cortex Image by the Max Planck Florida Institute for Neuroscience



Motor neurons Berkshire community college bioscience image library

Structure of a Typical Neuron



Picture from the Wikimedia Commons

- Dendrites are thin structures that arise from the cell body, branching multiple times, as a complex "dendritic tree"
- An axon (also called a nerve fiber) is a special cellular extension that arises from the cell body at a site called the axon hillock

How do neurons connect?



- From *synaptein* (Charles Scott Sherrington), from the Greek *syn*-(together) and *haptein* (to clasp)
- Specialized junctions through which neurons signal to each other and to non-neuronal cells such as those in muscles or glands
- Crucial to the biological computations that underlie perception and thought
- A huge number in human brain:
 - ♦ 10^{15} in young children
 - ♦ $10^{14} 5 \times 10^{14}$ for adults
- It happens at the level of the membranes of the cells

What happens at a synapse?



- Presynaptic: tip of an axon
- Postsynaptic: dendrite or cell body
- Presynaptic neurons secrete neurotransmitters (active zones)
- which bind to receptors from postsynaptic cells
- thanks to cell adhesion proteins in active zones
- and appears the postsynaptic density behind the postsynaptic membrane

What happens at a synapse?



Why are the neurotransmitters released?

Picture from the Wikimedia Commons

What happens at a synapse?



- The neurotransmitters are chemical messengers which transmit signals between neurons
- Stored in synaptic vesicles in the presynaptic axon
- They are released in response to a action potential
- Synaptic vesicles fuse with cell membrane
- And neurotransmitters diffuse and bind to receptors
- Receptors open nearby ion channels in the postsynaptic zone
- and flow of ions in or out changes membrane potential of postsynaptic neuron

How to describe the neural activity with mathematical models?

• Neural activity in terms of the membrane potentials

• Mathematical models to describe the membrane potential



Picture from the Wikimedia Commons

- Membrane potential: $V = V_{inside} - V_{outside}$
- Typical values in the range -40 mV to -70 mV
- Different ions: Potassium, Sodium, Chloride ...
 - Threshold potential Action potential



Action potential



Picture from the Wikimedia Commons

- The membrane potential starts out at -70mV (Resting potential)
- A stimulus is applied
- The membrane potential rapidly rises to a peak potential
- Then drops below the resting potential
- Remains in a refractory period
- Resting potential is reestablished

How to model membrane potential?

- Membrane potential is the electric potential difference across a cell's plasma membrane
- Membrane is polarized due to different charges inside and outside of the cell
- Influences in the membrane potential:
 - Permeability of the different ions
 - Different concentrations of the different ions
 - Ion pumps

Membrane potential can be modeled as an electric circuit

Different scales

- Microscopic (Particle Description): Very huge number of equations
- Probability density description:

f(t, x, v) Particle density at time t By the Max Planck Florida Institute for Neuroscience in variables (x, v)(in kinetic theory: position x with velocity v, in neuroscience, for instance: conductance x and voltage v)

Macroscopic (Hydrodynamic Description): System for the macroscopic quantities: momentum of *f* (in kinetic theory: density, momentum and temperature, in neuroscience, for instance: firing rate)



Electroencepalogram from the Wikimedia Commons

Neurophysiological phenomena

Relationship between neurophysiological phenomena and properties of the solutions of mathematical models



- Self-sustained oscillations are found in many brain areas, like the visual cortex and the olfactory cortex.
- Synchronization/asynchronization of the network:
 - blow-up
 - periodic solutions
 - asymptotic stability
- Epilepsy maybe related with blow up
- Multi-stability is related with:
 - visual perception
 - decision making

How to propose mathematical models to describe neurons?
Neuronal model of L. Lapicque (1907)



by Roman Biernacki With experiments on the frog sciatic nerve (with platinum plated electrodes) discovers

Membrane potential can be modeled as an electric circuit



Picture from the Wikimedia Commons

- The circuit consists of
 - conductors or resistors, representing the ion channels
 - batteries, representing the concentration gradients of the ions
 - capacitors, representing the ability of the membrane to store charge
- Relationship between the charge stored Q and potential V

Q = CV C is a proportionality constant

- Current is time derivative of charge
- *Kirchhoff's current* law states that the total current into the cell must sum to zero

<u>Ohm's Law</u>:

- V Potential difference (Voltage): Volts
- V = RI R Electrical Resistence: Ohms
 - *I* Electric Current: Amperes

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Therefore, the evolution in time: $C\frac{dV}{dt} = \frac{dI}{dt}$ equivalently

$$C_m \frac{dV}{dt} = I_{apply} \left(= \frac{dQ}{dt} \right) \qquad \begin{array}{c} C_m & \text{Capacitance: Faraday}(= sS) \\ I_{apply} & \text{Applied Current: Amperes} \\ Q & \text{Electric charge: Culombios} \end{array}$$

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$$I_{apply} = -I_{leakage} - I_{ions} + I_{ext}$$

Ordinary Differential Equations (microscopic description)

Microscopic level: different models

- Hodgkin-Huxley model
- Morris-Lecar model
- FitzHugh-Nagumo model
- Integrate-and-fire model

- Model propused by Alan Lloyd Hodking and Andrew Fielding Huxley
- Both together with John Carew Eccles were awarded the 1963 Nobel Prize in Physiology or Medicine "for their discoveries concerning the ionic mechanisms involved in excitation and inhibition in the peripheral and central portions of the nerve cell membrane"
- Their model describe the ionic mechanisms underlying the initiation and propagation of action potentials in the squid giant axon
- Video squid giant axon

They considered experiments using the voltage-clamping technique:

- The potential across the membrane is kept fixed at various voltages
- The mechanisms in the cell then react to this potential, and the short-time potential changes needed to counter them are then measured

$$C_m \frac{dV}{dt} = I_{apply} = -I_{leakage} - I_{ions} + I_{ext}$$

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- $I_{leakage}(V) = g_L(V V_L),$
 - g_L : leakage conductance (constant)
 - V_L : resting potential

$$C_m \frac{dV}{dt} = I_{apply} = -I_{leakage} - I_{ions} + I_{ext}$$

•
$$I_{leakage}(V) = g_L(V - V_L),$$

 g_L : leakage conductance (constant)

 V_L : resting potential

• $I_{ion}(V) = I_{Na}(V) + I_K(V)$

$$\diamond I_{Na}(V) = g_{Na}(V - V_{Na}),$$

 g_{Na} : Na conductance (depending on V)

 V_{Na} : reversal potential for Na

$$\diamond I_K(V) = g_K(V - V_K),$$

 g_k : K conductance (depending on V)

 V_K : reversal potential for K

Voltage-gated ion channels

- Ion channels can be thought of as having gates that open or close to regulate the flow of ions through them
- We can consider that the gates follow a Markov process, with transition rates from closed to open *α*, and from open to closed β



Evolution on time of the fraction of open channels *f* is given by

$$\frac{\mathrm{d}f}{\mathrm{d}t} = \alpha(1-f) - \beta f = \alpha - (\alpha + \beta)f = \frac{f_{\infty} - f}{\tau},$$

with $f_{\infty} = \frac{\alpha}{\alpha + \beta}$ and $\tau = \frac{1}{\alpha + \beta}$. Moreover, transition rates depend on the potential difference *V*:

$$\alpha = \alpha_0 e^{-\tilde{\alpha}V}, \quad \beta = \beta_0 e^{-\tilde{\beta}V} \quad \tilde{\alpha}, \tilde{\beta} > 0,$$

and then $f_{\infty}(V) == \frac{1}{1+e^{\frac{-(V-V_0)}{S_0}}}$ with

$$S_0 = \frac{1}{\tilde{\beta} - \tilde{\alpha}}$$
, and $V_0 = S_0 \ln\left(\frac{\beta_0}{\alpha_0}\right) = \frac{1}{\tilde{\beta} - \tilde{\alpha}} \ln\left(\frac{\beta_0}{\alpha_0}\right)$.

Evolution on time of the fraction of open channels *f* is given by

$$\frac{\mathrm{d}f}{\mathrm{d}t} = -\beta f + \alpha (1-f) = \alpha - (\alpha + \beta)f = \frac{f_{\infty} - f}{\tau},$$

We observe that $f_{\infty} = \frac{1}{1+e^{\frac{-(V-V_0)}{S_0}}}$ has a sigmoidal form and

therefore the gates can either be activating (if $S_0 > 0$) or inactivating (if $S_0 < 0$). In this sense V_0 can be considered as the threshold and S_0 the sensitivity of channel opening.



$$--V_0 = 2, S_0 = -2$$
 (inactivating)
--- $V_0 = 0, S_0 = 2$ (activating)

$$C_m \frac{dV}{dt} = I_{apply} = -I_{leakage} - I_{Na} - I_K + I_{ext}$$

• $I_{leakage}(V) = g_L(V - V_L),$

•
$$I_{Na}(V) = \bar{g}_{Na}m^3(V)h(V)(V - V_{Na})$$

•
$$I_K(V) = \bar{g}_K n(V)^4 (V - V_K)$$

 \bar{g}_{Na} and \bar{g}_K maximal value of the conductances m and n activation variables, and h inactivation variable (between 0 and 1) of the ions channels

$$\frac{dh}{dt} = \alpha_h(V)(1-h) - \beta_h(V)h$$
$$\frac{dm}{dt} = \alpha_m(V)(1-m) - \beta_m(V)m$$
$$\frac{dn}{dt} = \alpha_n(V)(1-n) - \beta_n(V)n$$

 $\alpha(V)$ and $\beta(V)$ are obtained experimentally using the voltage-clamping technique

$$C_m \frac{dV}{dt} = -g_L (V - V_L) - \bar{g}_{Na} m^3 h(V) (V - V_{Na}) - \bar{g}_K n(V)^4 (V - V_K) + I_{ext}$$

$$\frac{dh}{dt} = \alpha_h(V)(1-h) - \beta_h(V)h$$
$$\frac{dm}{dt} = \alpha_m(V)(1-m) - \beta_m(V)m$$
$$\frac{dn}{dt} = \alpha_n(V)(1-n) - \beta_n(V)n$$

 \bar{g}_{Na} and \bar{g}_{K} maximal value of the conductances

m, n and h activation/inactivation variables (between 0 and 1) of the ions channels

- Nonlinear system unsolved analytically
- Describes the action potential
- To describe the behaviour of a large number of neurons this model is very expensive

Exercise: Numerical study of the model

Hodgkin-Huxley, The J. of Physiology Vol. 116.4, 473-496 (1952)

Hodgkin-Huxley, The J. of Physiology Vol. 117.4, 500-544 (1952)

Membrane Potential and Stimulus Current



Membrane Potential and Stimulus Current



Membrane Potential and Stimulus Current





Simplifications of Hodgkin-Huxley model



Wikimedia Commons

- In 1981 Catherine Morris and Harold Lecar proposed a simplification of the Hodgkin-Huxley model
- Studing the barnacle muscle fibers subjected to constant current stimulation



Wikimedia Commons

- In 1981 Catherine Morris and Harold Lecar proposed a simplification of the Hodgkin-Huxley model
- Studing the barnacle muscle fibers subjected to constant current stimulation

- They consider two channels also, but in this case are Calcium and Potassium
- Again the activation variables are obtained experimentally

Morris-Lecar, Biophys. J. Vol. 35(1), 193-213 (1981)

$$C_m \frac{dV}{dt} = -g_L(V - V_L) - \bar{g}_{Ca}m(V)(V - V_{Ca}) - \bar{g}_Kn(V)(V - V_K) + I_{ext}$$
$$\frac{dm}{dt} = \lambda_m(V)(m_{\infty}(V) - m)$$
$$\frac{dn}{dt} = \lambda_n(V)(n_{\infty}(V) - n)$$

 $m_{\infty}(V)$ and $n_{\infty}(V)$ are the fraction of open calcium and potassium channels, respectively, at steady state, and λ_m , λ_n the rate for opening of calcium and potassium channels, respectively, and are obtained experimentally

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 $m_{\infty}(V)$ and $n_{\infty}(V)$ are the fraction of open calcium and potassium channels, respectively, at steady state, and λ_m , λ_n the rate for opening of calcium and potassium channels, respectively, and are obtained experimentally

- Reduces the Hodgkin-Huxley system to 3 equations
- Reproduces the oscillations of the action potential

Morris-Lecar, Biophys. J. Vol. 35(1), 193-213 (1981)

The authors propose a further simplification to reduce the system to two equations

$$C_m \frac{dV}{dt} = -g_L(V - V_L) - \bar{g}_{Ca} m_{\infty}(V)(V - V_{Ca}) - \bar{g}_K n(V)(V - V_K) + I_{ext}$$
$$\frac{dn}{dt} = \lambda_n(V)(n_{\infty}(V) - n),$$

where the calcium system is assumed to be so much faster than the potassium system so it is assumed $m(V) = m_{\infty}(V)$ (stationary)

We observe that the system can be written as

$$\frac{dV}{dt} = f(V, n)$$

$$\frac{dn}{dt} = g(V, n)$$
(-1)



- Other simplification is the FitzHugh–Nagumo model, developed by Richard FitzHugh in 1961
- and Jin-Ichi Nagumo et al. who created the equivalent circuit the following year, describes a prototype of an excitable system
- Previous models arise from the biophysics of neurons
- The origin of this model is phenomenological
- Phenomenological models only seek to capture the essence of the behaviour
- They tend to be more mathematically manageable than the others

Richard FitzHugh modified the van der Pol equations (he referred to these equations as the Bonhoeffer–van der Pol equations) for an electrical circuit with a linear capacitor, linear inductor, and nonlinear resistor in parallel

$$C\frac{dV}{dt} + F(V) + J = 0$$
$$L\frac{dJ}{dt} = V,$$

where *C* is the capacitance, *L* the inductance, F(V) a nonlinear current depending on the voltage, *V*, across the capacitor, and *J* the current through the inductor The system can be written as a second-order differential equation with unknown *V*

$$CV''(t) + F'(V)V'(t) + \frac{V(t)}{L} = 0$$

which is a modification of the second order linear equation

$$x^{\prime\prime} + kx^{\prime} + x = 0,$$

where instead of the damping coefficient, *k*, is considered a function of the solution

$$C\frac{dV}{dt} = V(V-a)(1-V) - w + I_{ext} =: f_1(V,w)$$
$$\frac{dw}{dt} = \beta V - w := f_2(V,w)$$

V : proxy for the membrane potential w : analogous the gating variables in the HH model $0 < a < 1, \beta, C > 0$ and $I_{ext} \in \mathbb{R}$

 Reduced system (2 equations) which models activation and desactivation dynamics of a spiking neuron

Exercise: Analysis of this system of two equations

FitzHugh, Biophys. J. Vol. 1, 445-466 (1961)

Nagumo-Arimoto-Yoshizawa, Proc. IRE. Vol. 50, 2061-2070 (1961)



Model for nerve fibre

- Previous models describe *local behaviour* of the electrical activity
- They are appropriate for fibres with relatively little spatial variation of biophysical properties, such as the squid giant axon
- To be model more realistic we consider a cell that is shaped as a long cylinder, or cable
- The current flow is along a single spatial dimension, *x*, the distance along the cable
- The membrane potential depends on the *x* variable and time *t*
- The cable equation is a partial differential equation that describes how the membrane potential *V*(*x*, *t*) depends on currents entering, leaving, and flowing within the neuron
Model for nerve fibre

Cable equation

$$C\frac{\partial V(x,t)}{\partial t} = D\frac{\partial^2 V(x,t)}{\partial x^2} - I_{\text{ion}} \quad D > 0$$

**What units does D have?

*I*_{ion} can be obtained from:

- Hodgkin-Huxley model
- Morris-Lecar model
- FitzHugh-Nagumo model

considering their right hand side in the equation for V

The system with FN model is used to study travelling waves in electrical activity, and have been used to model electrical activity in the heart, for example

FitzHugh's movie of nerve impulse propagation using computer animation techniques available around 1960

Previous models are known as conductance-based models and describe the membrane potential in terms of the ion channels

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These models describe the dynamics of the action potential accurate but they are very difficult to use for a large number of neurons, since they are very expensive

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We present now Integrate-and-Fire models which do not describe action potential but model the firing rate

Recall the equation for the membrane potential

$$C_m \, \frac{dV}{dt} = I_{apply}$$

considering $I_{apply} = -I_L + I$ $\boxed{I_L = g_L(V - V_L)}$ leakage current

- g_L leak conductance
- V_L resting potential

$$C_m \, \frac{dV}{dt} \, = \, -g_L(V - V_L) + I$$

Calling $\tau_m = C_m/g_L \approx 2ms$

$$\tau_m \frac{dV}{dt} = -(V - V_L) + \frac{I}{g_L}$$

$$\tau_m \frac{dV}{dt} = -(V - V_L) + \frac{I}{g_L}$$

- There are firing times t_{spike} : $V(t_{spike}) = V_{threshold}$
- Inmediately after t_{spike} the potential is reset: $V(t_{spike}^+) = V_{reset}$
- $V_L < V_{reset} < V_{threshold}$
- Typically $V_L \approx -70mV$, $V_{reset} \approx -60mV$ and $V_{threshold} \approx -50mV$
- Equilibrium: $V_{\infty} = V_L + \frac{I}{g_L}$
- If $V_{\infty} < V_{threshold}$ there are no spikes







 $\tau = 15, I = 1.5, \frac{1}{g_L} = 20$

Noise Neurons live in a noisy enviroment

Noise

- The above models describe a deterministic behaviour
- However opening and closing of channels is a probablistic event
- A spontaneous release of neurotransmitters occurs, leading to a random bombardment of small depolarizations and hyperpolarizations
- Noise in neural systems has been the subject of research since the early 1960s

See G. Bard Ermentrout & David H. Terman *Mathematical Foundations of Neuroscience* and references therein for further details

$$\tau_m \frac{dV}{dt} = -(V - V_L) + \frac{I}{g_L}$$
+
White noise
$$dV = \tau_m \left(\frac{I}{g_L} - (V - V_L)\right) dt + \sigma dB_t$$

We can simulate that stochastic system with this scheme

$$V_{n+1} = V_n + \tau_m \left(\frac{I}{g_L} - (V_n - V_L) \right) dt + \sigma \sqrt{dt} \mathcal{N}(0, 1)$$

The noise allows neurons to fire in the presence of subthreshold inputs

If a current is applied that will not cause the deterministic model to fire, the addition of zero mean noise can induce the neuron to fire



$$\tau = 15, I = 1.5, \frac{1}{g_L} = 10, \sigma = 2$$



$$\tau = 15, I = 1.5, \frac{1}{g_L} = 10, \sigma = 2$$



 $\tau = 15, I = 1.5, \frac{1}{g_L} = 20, \sigma = 2$

Leaky integrate and fire model with interaction

How to take into account the interaction between neurons?

$$C_m \frac{dV}{dt} = -g_L \left(V - V_L \right)$$

+ Interactions

$$C_m \frac{dV}{dt} = -g_L \left(V - V_L \right) + I(t)$$

- *I(t)*: Interactions of the neuron with the network (synapse)
- No constant input

Leaky integrate and fire model with interaction

$$C_m \frac{dV}{dt} = -g_L \left(V - V_L \right) + I(t)$$

•
$$I(t) = J_E \sum_{i=1}^{C_E} \sum_j \delta(t - t_{Ej}^i - d) - J_I \sum_{i=1}^{C_I} \sum_j \delta(t - t_{Ij}^i - d)$$

- \diamond *E*, *I*: Excitatory, Inhibitory neurons
- \downarrow *J_E*, *J_I*: strength of the synapses
- \diamond C_E , C_I : total number of presynaptic neurons
- $t_{Ej'}^i, t_{Ij}^i$: times of the j^{th} -spike coming from the i^{th} -presynaptic neuron
- ♦ d: transmission delay
- The incoming synaptic current is a stochastic process
- Noisy leaky integrate and fire model

Partial Differential Equations (Probability density description-mesoscopic description)

Mean-field models

- What is the behaviour of a large number of neurons?
- Mesoscopic description in terms of density of neurons
- The unknown, *p*, is the probability of finding a neuron at time *t*
 - \diamond with voltage v
 - with 'state' s. 'state' is the *time elapsed* since last spike
 ...
- If the number of neurons is very large, is *p* a solution to any equation?
- If the answer is yes, the equation is called a mesoscopic o mean-field

Advantages of mesoscopic models

- Drastic reduction of the number of equations
- The mesoscopic equation is easier to study than the microscopic system
- The computational cost to numerically solve the mesoscopic equation is lower than that required to solve the macroscopic system
- It is possible to obtain macroscopic quantities

Mean field limits for 'particles' systems, where particles could be:

- Physics: gases, electrons, ...
- Biology: cells, virus, ...
- Economy: agents in a market, ...

Example 1

Particle system

$$C_m \frac{dV_i}{dt} = I \quad i = 1, \dots, N$$

The density of neurons p(t, v) satisfies

 $C_m \partial_t p + I \partial_v p = 0$

which is independent on N, so the limit equation with $N \rightarrow \infty$ is the same equation

For each *i*: $V_i(t) = \frac{V_i(0)+It}{C_m}$, therefore $p(V_i(t), t) = p(V_i(0), 0)$

$$0 = \frac{dp(V_i(t), t)}{dt} = \partial_t p(V_i(t), t) + \frac{I}{C_m} \partial_v p(V_i(t), t) = 0$$

Example 2

Particle system

$$C_m \frac{dV_i}{dt} = I - gV_i \quad i = 1, \dots, N$$

Mesoscopic model

 $C_m \partial_t p + \partial_v \left((I - gv) p \right) = 0$

With noise

- Particle systems is a stochastic system
- Probability density of neurons is the density of a stochastic process
- Does the probability density of neurons become deterministic as the number of neurons tends to ∞? (propagation of chaos)
- If the case, does it satisfy a PDE?

Example

Particle system: $\frac{dV_i}{dt} = \sigma dB_t^i$ i = 1, ..., N

Mesoscopic model: $\partial_t p - \frac{\sigma^2}{2} \partial_v^2 p = 0$

The unknown, *p*, is the probability of finding a neuron at time *t*

- If spike trains follow Poisson processes ~> Nonlinear Fokker-Planck equations
 - p(v, t) is the probability of finding a neuron at time t
 with voltage v

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Quiñinao, Acta Applicandae Mathematicae, 146:29-55, (2016)

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Dumont, Henry and Tarniceriu give some relationships between both PDE models

Dumont-Henry-Tarniceriu, J. Theor Biol, 406, 31-41. (2016)

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Nonlinear Noisy Leaky Integrate and Fire (NNLIF)

(Nonlinear Fokker-Planck equations)

Neural phenomena

- Networks are composed of excitatory and inhibitory neurons
- When the membrane potential reaches a threshold value V_F, the neurons emit an action potential (spike) and their voltage values return to a reset value V_R. (V_R < V_F)
- Between the emission and reception of the spikes among neurons there are some *transmission delays*
- During a certain time (*refractory period*) the neurons do not respond to stimuli

There is a family of NNLIF models in terms of the different phenomena that take into account

Neural phenomena

Let's start with

- Networks are on average excitatory or inhibitory
- When the membrane potential reaches a threshold value V_F, the neurons emit an action potential (spike) and their voltage values return to a reset value V_R. (V_R < V_F)
- Between the emission and reception of the spikes among neurons there are some *transmission delays*
- During a certain time (*refractory period*) the neurons do not respond to stimuli

Noisy Leaky Integrate-and-fire model

NLIF Model

• *I*(*t*): Interactions of the neuron with the network (synapse)

Noisy Leaky Integrate-and-fire model

- NLIF Model
- *I*(*t*): Interactions of the neuron with the network (synapse)
- $I(t) = J_E \sum_{i=1}^{C_E} \sum_j \delta(t t_{Ej}^i) J_I \sum_{i=1}^{C_I} \sum_j \delta(t t_{Ij}^i)$
 - E, I: Excitatory, Inhibitory neurons
 - \downarrow J_E, J_I: strength of the synapses
 - \diamond C_E, C_I: total number of presynaptic neurons
 - $t_{Ej'}^{i}$, t_{Ij}^{i} : times of the j^{th} -spike coming from the i^{th} -presynaptic neuron
Noisy Leaky Integrate-and-fire model

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 - $t_{Ej'}^{i}$ t_{Ij}^{i} : times of the j^{th} -spike coming from the i^{th} -presynaptic neuron
- Stochastic process.-
 - Each neuron spikes according to a stationary Poisson process with constant probability of emitting a spike per unit time v
 - All these processes are assumed to be independent between neurons
 - $\mu_C = b\nu$ average value of the current $(b = C_E J_E C_I J_I)$
 - $\circ \ \sigma_C^2 = (C_E J_E^2 + C_I J_I^2) \nu \text{ variance of the current}$

Noisy Leaky Integrate-and-fire model

Any typical neuron of the network:

$$dV = (-V + V_L + \mu_c) dt + \sigma_C dB_t$$

 $(\mu_C = b\nu, \, \sigma_C^2 = (C_E J_E^2 + C_I J_I^2)\nu, \\ C_m = g_L = 1)$

 $V(t_{spike}^{-}) = V_F$ and $V(t_{spike}^{+}) = V_R$, t_{spike} the firing time Assuming:

- Diffusion approximation of the synaptic current with the same mean and variance as the Poissonian spike-train process
- A network sparse random connectivity
- Small synaptic strength compared to the firing threshold

Brunel-Hakim, Neural Comp. Vol. 11, 1621-1671 (1999)

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Mattia-Del Giudice, Phys. Rev. E, Vol. 66, 051917 (2002)

Noisy Leaky Integrate-and-fire model

• Diffusion approximation $(\mu_C = b\nu, \sigma_C^2 = (C_E J_E^2 + C_I J_I^2)\nu, C_m = g_L = 1)$

 $dV = (-V + V_L + \mu_c) dt + \sigma_C dB_t$

• Firing rate: Probability of firing per unit time of the Poissonian spike train

 $\nu = \nu_{ext} + N(t - d)$

N(t) mean firing rate of the network

- N(t) is computed as the flux of neurons across the threshold or firing voltage V_{threshold} = V_F
- *d* is the transmission delay

Brunel-Hakim, Neural Comp. Vol. 11, 1621-1671 (1999)

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Sirovich-Omurtag-Lubliner, Network: Computation in Neural Systems, Vol. 17, 3-29, (2006)

Mattia-Del Giudice, Phys. Rev. E, Vol. 66, 051917 (2002)

$$\begin{array}{l} \text{NNLIF model with } d = 0\\ \frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v}\left[h(v,N(t))p(v,t)\right] - a\left(N(t)\right)\frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v-V_R)N(t) \end{array}$$

NNLIF model with d = 0 $\frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v} \left[h(v,N(t))p(v,t)\right] - a(N(t))\frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v - V_R)N(t)$

• $v \in (-\infty, V_F]$ V_R : Reset potential V_F : Threshold potential

- h(v, N) = -v + bN(t)
- $a(N) = a_0 + a_1 N$ $a_0 > 0, a_1 \ge 0$

$\begin{array}{l} NNLIF \ model \ with \ d = 0 \\ \frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v} \left[h(v,N(t))p(v,t)\right] - a(N(t)) \frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v - V_R)N(t) \end{array}$

- $v \in (-\infty, V_F]$ V_R : Reset potential V_F : Threshold potential
- h(v, N(t)) = -v + bN(t) excitatory/inhibitory network (b>0 or b<0)
- $a(N) = a_0 + a_1 N$ $a_0 > 0, a_1 \ge 0$ we generally consider a(N) = a = 1

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Boundary conditions

- $p(V_F, t) = 0$
- $p(-\infty, t) = 0$

•
$$\frac{\partial p}{\partial v}(V_R^-, t) - \frac{\partial p}{\partial v}(V_R^+, t) = \frac{N(t)}{a(N(t))}$$

 $\begin{array}{l} NNLIF \ model \ with \ d = 0 \\ \frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v} \left[h(v,N(t))p(v,t)\right] - a(N(t))\frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v - V_R)N(t) \end{array}$

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Boundary conditions

- $p(V_F, t) = 0$ • $p(-\infty, t) = 0$ • $\frac{\partial p}{\partial v}(V_R^-, t) - \frac{\partial p}{\partial v}(V_R^+, t) = \frac{N(t)}{a(N(t))}$
- $N(t) := -a(N(t))\frac{\partial p}{\partial v}(V_F, t) \ge 0 \iff \text{Nonlinear system!}$ Firing rate Conservation of mass $\int_{-\infty}^{V_F} p(v, t) dv = 1$ Exercise

Brunel-Hakim, Neural Comp. Vol. 11, 1621-1671 (1999)

C-Carrillo-Perthame, The Journal of Mathematical Neuroscience, 1:7. (2011)

NNLIF model with d > 0

$$\frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v} \begin{bmatrix} h(v,N(t-d)) & p(v,t) \end{bmatrix} - a(N(t-d)) & \frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v-V_R)N(t) \\ \text{transmission delay} & \text{transmission delay} \end{bmatrix}$$

$$v \in (-\infty, V_F] \quad V_R: \text{Reset potential} \quad V_F: \text{ Threshold potential} \\ h(v,N(t)) = -v + bN \text{ excitatory/inhibitory network (b>0 or b<0)} \\ a(N) = a_0 + a_1 N \quad a_0 > 0, a_1 \ge 0 \text{ we generally consider } a(N) = a = 1 \\ \hline Boundary \text{ conditions}} \\ p(V_F,t) = 0 \\ p(-\infty,t) = 0 \\ N(t) := -a(N(t-d))\frac{\partial p}{\partial v}(V_F,t) \ge 0 \quad \Leftarrow \text{ Nonlinear system!} \\ \text{Firing rate} \quad \text{Conservation of mass } \int_{-\infty}^{V_F} p(v,t)dv = 1 \\ \hline \text{Exercise} \end{bmatrix}$$

Analytical properties

- Blow up
- Transmission delay avoids blow up
- Existence results
- Steady states
- Long time behaviour

Theorem (C-Carrillo-Perthame, 2011) Assuming:

- $h(v, N) + v \ge bN, \ 0 < a_m \le a(N) \ (-\infty < v \le V_F \ and \ N \ge 0)$
- *b* > 0 average-excitatory network

If the initial data is concentrated enough around $v = V_F$ there are no global-in-time weak solutions

Theorem (C-Carrillo-Perthame, 2011) Assuming:

- $h(v, N) + v \ge bN, \ 0 < a_m \le a(N) \ (-\infty < v \le V_F \ and \ N \ge 0)$
- *b* > 0 average-excitatory network

If the initial data is concentrated enough around $v = V_F$ there are no global-in-time weak solutions

The solutions blow up when ...

- For *b* fixed: the initial condition is concentrated enough around *V_F*
- For p^0 fixed: *b*, the connectivity parameter, is large enough

Concentrated enough around V_F

$$\int_{-\infty}^{V_F} e^{\mu v} p^0(v) \, dv \ge \frac{e^{\mu V_F} - e^{\mu V_R}}{b \, \mu} =: \lambda$$

choosing
$$\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$$

proof

Roux-Salort, 2021: All solutions blow-up if b is large enough

. – p.50/95

Carrillo-González-Gualdani-Schonbek^{*} analyze the global existence of classical solutions (d = 0 and a = 1)

- For inhibitory networks: Global classical solutions
- For excitatory networks: Local well-posedness of classical solutions
- Blow up criterium:

 $T^* = \sup \{t > 0 : N(t) < \infty\}$

- *T*^{*}: maximal existence time
 - For inhibitory networks: $T^* = \infty$
 - For excitatory networks: there exist classical solutions which blow up at finite time T* and N diverges

*Carrillo-González-Gualdani-Schonbek, Comm. in PDEs, Vol. 38(3), 385-409, (2013)

Delarue-Inglis-Rubenthaler-Tanré, The Annals of Applied Probability, 25(4), 2096-2133 (2015).

. - p.51/95

Delarue-Inglis-Rubenthaler-Tanré, Stoch. Proc. Appl., 125(6), 2451-2492 (2015)

Blow-up

Distribution functions p(v, t) for $a \equiv 1$ and b = 3 at different times



. – p.51/95

$$\frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v} \left[h\left(v,N(t)\right) p(v,t) \right] - a\left(N(t)\right) \frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v - V_R)N(t)$$

- $v \in (-\infty, V_F]$
- h(v, N(t)) = -v + bN
- $a(N) = a_0 + a_1 N$ $a_0 > 0, a_1 \ge 0$

$$\frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v} \left[h(v,N(t-d))p(v,t) \right] - a(N(t-d)) \frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v-V_R)N(t)$$

- $v \in (-\infty, V_F]$
- h(v, N(t-d)) = -v + bN(t-d)
- $a(N(t-d)) = a_0 + a_1N(t-d)$ $a_0 > 0, a_1 \ge 0$

$d \ge 0$ is the transmission delay

C-Schneider, ESAIM: M2AN, Vol 52(5), 1733-1761, (2018)

C-Roux-Salort-Schneider, Commun Part Diff Eq, Vol 44(12), 1358-1386 (2019)

 $a \equiv 1$ and b = 0.5



d = 0

d > 0

Firing rate with delay, d > 0 for two different situations: b small (only one steady state) and b large (no steady states)



C-Schneider, ESAIM: M2AN, Vol 52(5), 1733-1761, (2018)

C-Roux-Salort-Schneider, Commun Part Diff Eq, Vol 44(12), 1358-1386 (2019)

Difficulty to prove the global existence

- Inhibitory case: The criterium for the maximal time of existence directly derives that the firing rate is uniformly bounded for every time, obtaining the global existence of solution
- Excitatory case: The previous procedure is not possible, since the firing rate sometimes is not uniformly bounded.

C-Roux-Salort-Schneider, Commun Part Diff Eq, Vol 44(12), 1358-1386 (2019) Carrillo-González-Gualdani-Schonbek, Comm. in PDEs, Vol. 38(3), 385-409, (2013) Carrillo-Perthame-Salort-Smets, Nonlinearity 28 3365 (2015)

Proof of the global existence of solution (d > 0**)**

- 1. Rewriting as a Stefan like problem
- 2. Local existence by means of
 - Integral formulation
 - Fixed point theorem
- 3. Key result: Maximal time of existence
- 4. super solutions and global existence result



We will focus on the case of a(N) = a constant

$$\frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v} \left[(-v + bN(t-d)) p(v,t) \right] - a \frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v - V_R)N(t)$$

$$p_{\infty} \text{ steady state satisfies}$$
$$\frac{\partial}{\partial v} \left[(v - bN)p + a \frac{\partial}{\partial v} p(v) + NH(v - V_R) \right] = 0$$

in the sense of distributions, with H being the Heaviside function

Therefore,

$$(v - bN_{\infty})p_{\infty} + a\frac{\partial p_{\infty}}{\partial v} + N_{\infty}H(v - V_R) = C$$

Therefore,

$$(v - bN_{\infty})p_{\infty} + a\frac{\partial p_{\infty}}{\partial v} + N_{\infty}H(v - V_R) = C$$

Definition of N_{∞} + Dirichlet boundary condition $\implies C = 0$

Then (easy exercise)

$$p_{\infty}(v) = \frac{N_{\infty}}{a}e^{-\frac{(v-bN_{\infty})^2}{2a}} \int_{v}^{V_F} e^{\frac{(w-bN_{\infty})^2}{2a}} H[w-V_R]dw$$

$$p_{\infty}(v) = \frac{N_{\infty}}{a} e^{-\frac{(v-bN_{\infty})^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{(w-bN_{\infty})^2}{2a}} dw$$

To determine p_{∞} we need to know N_{∞}

$$p_{\infty}(v) = \frac{N_{\infty}}{a} e^{-\frac{(v-bN_{\infty})^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{(w-bN_{\infty})^2}{2a}} dw$$

Using the conservation law, $\int_{\infty}^{V_F} p_{\infty}(v) dv = 1$, we obtain the following implicit equation for N_{∞}

$$\frac{a}{N_{\infty}} = \int_{-\infty}^{V_F} \left[e^{-\frac{(v-bN_{\infty})^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{(w-bN_{\infty})^2}{2a}} dw \right] dv$$

Linear case (b = 0)

$$\frac{a}{N_{\infty}} = \int_{-\infty}^{V_F} \left[e^{-\frac{v^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{w^2}{2a}} dw \right] dv$$

and there is unique stationary state p_{∞} given by

$$p_{\infty}(v) = \frac{N_{\infty}}{a} e^{-\frac{v^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{w^2}{2a}} dw$$

with

$$N_{\infty} = \frac{a}{\int_{-\infty}^{V_F} \left[e^{-\frac{v^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{w^2}{2a}} dw \right] dv}$$

Non-linear case $(b \neq 0)$

Question: Number of solutions to

$$\frac{a}{N} = \int_{-\infty}^{V_F} \left[e^{-\frac{(v-bN)^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{(w-bN)^2}{2a}} dw \right] dv ?$$

$$N = \frac{1}{I(N)} \iff NI(N) = 1 \iff \frac{1}{N} = I(N),$$

with

$$I(N) := \frac{1}{a} \int_{-\infty}^{V_F} \left[e^{-\frac{(v-bN)^2}{2a}} \int_{\max(v,V_R)}^{V_F} e^{\frac{(w-bN)^2}{2a}} dw \right] dv$$

With the change of variables:

$$z = \frac{v - bN}{\sqrt{a}}, \quad u = \frac{w - bN}{\sqrt{a}}, \quad w_F = \frac{V_F - bN}{\sqrt{a}}, \quad w_R = \frac{V_R - bN}{\sqrt{a}}$$
$$I(N) = \int_{-\infty}^{w_F} \left[e^{-\frac{z^2}{2}} \int_{\max(z, w_R)}^{w_F} e^{\frac{u^2}{2}} du \right] dz.$$

And with the new change $s = \frac{z-u}{2}$ and $\bar{s} = \frac{z+u}{2}$

$$I(N) = \int_0^\infty e^{-s^2/2} e^{-\frac{sbN}{\sqrt{a}}} \frac{e^{\frac{sV_F}{\sqrt{a}}} - e^{\frac{sV_R}{\sqrt{a}}}}{s} ds$$

Thus we find the steady states if find N solution to

$$\left(\begin{array}{c} \frac{1}{N} = I(N), \\ I(N) = \int_0^\infty e^{-s^2/2} e^{-\frac{sbN}{\sqrt{a}}} \frac{e^{\frac{sV_F}{\sqrt{a}}} - e^{\frac{sV_R}{\sqrt{a}}}}{s} \, ds. \end{array} \right)$$

(The details can be computed as exercise)

. – p.55/95

Properties of I(N)

- $I(0) < \infty$
- For all integers $k \ge 1$,

$$I^{(k)}(N) = (-1)^k \left(\frac{b}{\sqrt{a}}\right)^k \int_0^\infty e^{-s^2/2} s^{k-1} \left(e^{s w_F} - e^{s w_R}\right) ds \,.$$

- b < 0: *I* is an increasing strictly convex function and $\lim_{N\to\infty} I(N) = \infty$
- b > 0: *I* is a decreasing convex function and $\lim_{N\to\infty} I(N) = 0$, $\lim_{N\to\infty} N I(N) = \frac{V_F - V_R}{b}$. So when $N \to \infty$:

•
$$I(N) < \frac{1}{N}$$
 if $\frac{V_F - V_R}{b} < 1$

•
$$I(N) > \frac{1}{N}$$
 if $\frac{V_F - V_R}{b} > 1$

Exercise: prove these properties. (Hint: follow steps in C-Carrillo-Perthame, 2011) -p.55/95

Number of steady states in terms of connectivity parameter *b*

(C-Carrillo-Perthame, 2011):

- Average-inhibitory network (b < 0): there is a unique steady state
- Average-excitatory network (b > 0):
 - High connectivity: there is no steady state
 - Small connectivity: there is a unique steady state
 - Between small and high connectivity: at least one or at least two steady states

Function $\frac{1}{I(N)}$ is plotted against the function N for b < 0



Function $\frac{1}{I(N)}$ is plotted against the function N for b > 0



Theorem Assume a(N) = a is constant

- *i)* For *b* < 0 and *b* > 0 small enough there is a unique steady state
- *ii)* Under either the condition $0 < b < V_F V_R$ or the condition $0 < 2ab < (V_F V_R)^2 V_R$, there exists at least one steady state solution
- iii) If both $0 < 2ab < (V_F V_R)^2 V_R$ and $b > V_F V_R$ hold, then there are at least two steady states
- *iv)* There is no steady state under the high connectivity condition $b > max(2(V_F V_R), 2V_F I(0))$

Exercise: Proof. (Hint: follow steps in C-Carrillo-Perthame, 2011)

Are the steady states stable?
- Entropy dissipation method is a technique for studying the long-term behaviour of some PDE systems
- The idea is to find decreasing functionals (Lyapunov functionals)
- Originally it had a physical basis, physical entropy (*H*-Theorem for Boltzmann equation (gases dynamics))
 - For physicists, the functional is increasing

- The convergence is proved in terms of this functional: the distance to the equilibrium is given by the relative entropy
- Can it be traumatic for mathematicians whose preferred distance is L¹ norm?
 - Sometime is posible to prove that convergence in terms of the entropy implies convergence in L¹
 - Csizár-Kullback-Pinsker inequality:

$$\frac{1}{2} \|f - g\|_{L^1}^2 \le \int f \log \frac{f}{g}$$

 $H(f|g) := \int f \log \frac{f}{g}$ relative entropy

(See these notes of Jose Cañizo for more details about this inequality)

<u>Scheme</u>

Consider a *entropy functional*, *E*(*f*(*t*, ·)), which can be applied to any function, solution or not of the equation, such that, if *f* is a solution of the system,

$$\frac{d}{dt}E(f(t,\cdot)) = -D(f(t,\cdot)) \le 0,$$

 $D((f, \cdot))$ is called entropy production

 \diamond it has a unique minimum at the equilibrium $f_{\infty}(\cdot)$

- Consider the *relative entropy* $E[f|f_{\infty}](t) := E(f(t, \cdot)) E(f_{\infty}(\cdot)) \ge 0$
- Try to control entropy production by the entropy (entropy-entropy production inequality)

 $D(f) \ge \Phi(E[f|f_\infty])$

with $H \mapsto \Phi(H)$ some continuous function, strictly positive when H > 0

Finally

 $\frac{d}{dt}E[f|f_{\infty}](t) = -D(f(t, \cdot)) \le -\Phi(E[f|f_{\infty}])$

Entropy dissipation method $\frac{d}{dt}E[f|f_{\infty}](t) = -D(f(t, \cdot)) \leq -\Phi(E[f|f_{\infty}])$

• Example 1: $\Phi(H) = \alpha H$

$$\frac{d}{dt}E[f|f_{\infty}](t) = \leq -\Phi(E[f|f_{\infty}]) = -\alpha E[f|f_{\infty}] \Rightarrow E[f|f_{\infty}] \leq E[f|f_{\infty}](0)e^{-\alpha t}$$

- Example 2: $\Phi(H) = CH^{1+\alpha}$, $C, \alpha > 0$ Then the entropy going down like $O(t^{-1/\alpha})$ (polynomial rate of convergence to equilibrium)
- Example 3: we study the linear NNLIF equation

Relative entropy

$$E(t) := \int_{-\infty}^{V_F} p_{\infty}(v) G\left(\frac{p(v,t)}{p_{\infty}(v)}\right) dv$$

G convex function

- $\frac{dE(t)}{dt} \le 0$ Entropy production
- Control the entropy production in terms of the entropy

$$\frac{dE(t)}{dt} \le -\mu E(t), \quad \mu > 0$$

In this step Poincaré's inequality (see these notes of Jose Cañizo) helps (considering $G(x) = (x - 1)^2$)

$$\gamma \int_{-\infty}^{V_F} p_{\infty}(v) \left(\frac{p(v,t)}{p_{\infty}(v)} - 1\right)^2 dv \le \int_{-\infty}^{V_F} p_{\infty}(v) \left(\frac{\partial}{\partial v} \frac{p(v,t)}{p_{\infty}(v)}\right)^2 dv$$

Gronwall's inequality gives the result:

$$E(t) \le e^{-\mu t} E(0), \quad \mu > 0$$

. - p.57/95

Case linear b=0

For any smooth convex function $G : \mathbb{R}^+ \longrightarrow \mathbb{R}$

$$-\frac{d}{dt}\int_{-\infty}^{V_F} p_{\infty}(v)G\left(\frac{p(v,t)}{p_{\infty}(v)}\right)dv =$$

$$N_{\infty} \left[G\left(\frac{N(t)}{N_{\infty}}\right) - G\left(\frac{p(v,t)}{p_{\infty}(v)}\right) - \left(\frac{N(t)}{N_{\infty}} - \frac{p(v,t)}{p_{\infty}(v)}\right) G'\left(\frac{p(v,t)}{p_{\infty}(v)}\right) \right] \Big|_{V_{R}} + a_{0} \int_{-\infty}^{V_{F}} p_{\infty}(v) \; G''\left(\frac{p(v,t)}{p_{\infty}(v)}\right) \left[\frac{\partial}{\partial v}\left(\frac{p(v,t)}{p_{\infty}(v)}\right)\right]^{2} \; dv \geq 0$$

Exercise: Proof

Case linear b=0

Theorem [Exponential decay] (C-Carrillo-Perthame) Fast-decaying solutions verifying $p^0(v) \le C^0 p_{\infty}(v)$ for some $C^0 > 0$, satisfy

$$\int_{-\infty}^{V_F} p_{\infty}(v) \left(\frac{p(v,t) - p_{\infty}(v)}{p_{\infty}(v)}\right)^2 dv \le$$
$$e^{-2a_0vt} \int_{-\infty}^{V_F} p_{\infty}(v) \left(\frac{p^0(v) - p_{\infty}(v)}{p_{\infty}(v)}\right)^2 dv.$$

(considering $G(x) = (x - 1)^2$)

Case non linear $b \neq 0$

- C-Carrillo-Perthame: Numerical analysis
- Carrillo-Perthame-Salort-Smets: Local asymptotic stability for stationary states for |b| small
- C-Roux-Salort-Schneider: Local asymptotic stability for stationary states for |b| small and d > 0

Exercise: Compute $\frac{d}{dt} \int_{-\infty}^{V_F} p_{\infty}(v) G\left(\frac{p(v,t)}{p_{\infty}(v)}\right) dv$ in the nonlinear case $(b \neq 0)$ (G convex smooth function)

Carrillo-Perthame-Salort-Smets, Nonlinearity 28.9 (2015): 3365.

C-Roux-Salort-Schneider, Commun Part Diff Eq, Vol 44(12), 1358-1386 (2019)

Numerical results Firing rates N(t) for $a \equiv 1, d = 0$



Top left: b = 0.5 Top right: b = 3 Bottom left: b = 1.5 Bottom right: b = -1.5

What happens when the connectivity is high?



Considering $G(x) = (x - 1)^2$ and controlling the nonlinear term with L^2 estimates on N:

No answer using entropy method

- Without delay d = 0 and |b| small: Carrillo-Perthame-Salort-Smets, 2015
- With delay d > 0 and |b| small: C-Roux-Salort-Schneider, 2019

To answer the question, we first analyzed this other one

What happens after the blow-up phenomenon?

PDE description: blow-up situations

Without delay



. – p.63/95

To answer we have to go back to the microscopic description

Any typical neuron of the network becomes

 $dV(t) = -\left(V(t) + bN(t-d)\right)dt + \sqrt{2a}dB(t),$

B(t) the standard Brownian motion

 $V(t_{spike}^{-}) = V_F$ and $V(t_{spike}^{+}) = V_R$, with t_{spike} the firing time.

To answer we have to go back to the microscopic description

Any typical neuron of the network becomes

 $dV(t) = -\left(V(t) + bN(t-d)\right)dt + \sqrt{2a}dB(t),$

B(t) the standard Brownian motion

 $V(t_{spike}^{-}) = V_F$ and $V(t_{spike}^{+}) = V_R$, with t_{spike} the firing time.

- N(t) = e'(t)
- $e(t) = \lim_{N \to \infty} \frac{1}{N} \sum_{j}^{N} \sum_{k} 1_{\{\tau_{k}^{j} \le t\}}$ the theoretical expected number of spike times by a typical neuron

•
$$(\tau_k^j)_{k\geq 1}$$
 sequence of spike times

Delarue-Inglis-Rubenthaler-Tanré, Ann. Appl. Probab., 25(4), 2096-2133 (2015) Delarue-Inglis-Rubenthaler-Tanré, Stoch. Proc. Appl., 125(6), 2451-2492 (2015)

What happens after the blow-up phenomenon?

To answer we study the particle system numerically (C-RamosLora, 2021)

Sometimes systems tend to "plateau" distributions after the blow-up, which means that the membranes potential tend to be uniformly distributed in the interval (V_R, V_F)



Numerical tests to set the number of neurons

1 N=800 N=8000 Normalized particle density 8.0 N=80000 N=800000 0.6 0.4 0.2 0 -3 -2 0 2 -4 -1

b = 1.5. The system starts with a Gaussian initial condition and evolves towards a steady state. Distribution at time t = 0.5

. – p.66/95

Numerical tests to set the number of neurons



b = 1. A very singular situation where neurons are evenly distributed between V_R and V_F .

Distribution at time t = 0.005

. – p.66/95

System behaviour after the blow-up depends on the connectivity parameter *b*:

- Weakly connected (b < V_F V_R): Tends to its unique steady state after blow-up
- Highly connected $(V_F V_R \le b)$: "Plateau" distributions appear when synaptic delays are taken into account.
 - No steady states case: Tends to a "plateau" distribution
 - Two steady states case: Bistability between the steady state with the lowest firing rate and the "plateau" state
 - ◇ The limiting case $b = V_F V_R$: Tends to a "plateau" distribution under blow-up situations, either without synaptic delay or with a very small delay value. For a high enough delay the system tends to the stationary state

Relationship with physical solutions

(Delarue-Inglis-Rubenthaler-

Physical solutions for SDE model

At microscopic level the notion of solution was extended to physical solutions (Delarue-Inglis-Rubenthaler-Tanré):

- Main difference: regularity of the expectation e(t):
 - Continuous for classical solutions
 - Can present certain positive jump discontinuities for physical solutions
- Neurophysiologically:
 - \diamond Classical notion: neurons only fire when they reach V_F
 - Physical notion: neurons can fire if their membrane potentials are close to V_F
- Existence:
 - Non global existence for classical solutions (without delay)
 - ◇ Global existence even after the blow-up occurs for physical solutions The notion of physical solution make sense for weakly connected network (*b* < V_F − V_R), because neurons cannot fire more than once at the same time

Delarue-Inglis-Rubenthaler-Tanré, Ann. Appl. Probab., 25(4), 2096-2133 (2015) Delarue-Inglis-Rubenthaler-Tanré, Stoch. Proc. Appl., 125(6), 2451-2492 (2015)

Numerical simulations

What happens after blow-up?

(Fixed parameters: $V_R = 1$, $V_F = 2$, a = 1)

Particle system description

Blow-up situation: $b < V_F - V_R = 1$, d = 0. Physical solution



Particle system description

Blow-up situation: $b > V_F - V_R = 1$, d = 0. No physical solutions



Trivial solutions appears depending on *b*

Under what situations do "plateau" states appear?

Limiting case: $b = V_F - V_R$ video



Without delay

With very small delay=0.0001

"Plateau" states desappear for large delays if $b = V_F - V_R$



. – p.73/95



 $b = 1.5 > V_F - V_R$ two steady states with delay

 $b = 2.2 > V_F - V_R$ no steady states with delay



Numerical simulations show

The notion of physical solution make sense for weakly connected network ($b < V_F - V_R$), because neurons cannot fire more than once at the same time What happens after system synchronization depends on the connectivity parameter *b*:

- Without delay:
 - ◊ b < V_F V_R: the system is reset to V_R and tends to the steady state
 - ◊ b > V_F V_R: the system collapse and tends to a "trivial" state.
 - $b = V_F V_R$: the system tends to a "plateau" state.
- With delay:
 - ◊ b > V_F V_R: System tends towards a "plateau" distribution, even when there are no steady states
 - ◊ b = V_F V_R: System tends to a "plateau" state, unless the value of the delay is too large, in which case it tends to the steady state

Numerical simulations show

Therefore:

- Physical solution tends to its unique steady state after blow-up
- Limiting case $b = V_F V_R$:
 - ♦ "Plateau" profile coincides with the stationary profile, with $N \rightarrow \infty$.
 - System tends to:
 - a "plateau" distribution under blow-up situations, either without synaptic delay or with a very small delay value
 - the stationary state for a high enough delay

Pseudo equilibria

Discrete description for system with large transmission delay

Quick simulations give accurate information about the NNLIF system

$$\frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v}\left[(-v + bN(t-d))p(v,t)\right] - a\frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v - V_R)N(t)$$

Steady states

$$\frac{\partial}{\partial v} \left[(-v + bN_{\infty})p_{\infty}(v) \right] - a \frac{\partial^2 p_{\infty}}{\partial v^2}(v) = \delta(v - V_R)N_{\infty}$$

Using boundary conditions and conservation of mass

$$p_{\infty}(v) = \frac{N_{\infty}}{a} e^{-\frac{(v-bN_{\infty})^2}{2a}} \int_{max(v,V_R)}^{V_F} e^{\frac{(w-bN_{\infty})^2}{2a}} dw,$$

where $N_{\infty} = \frac{1}{I(N_{\infty})}$ (Implicit equation for N_{∞}) $I(N) := a^{-1} \left(\int_{-\infty}^{V_F} e^{-\frac{(v-bN)^2}{2a}} \int_{max(v,V_R)}^{V_F} e^{\frac{(w-bN)^2}{2a}} dw dv \right)$



Inhibitory networks: a unique steady state

Excitatory networks: depending on the connectivity parameter *b*: one, two or none steady state

Pseudo equilibria

$$p_{N}(v) = \frac{\tilde{N}_{\infty}}{a} e^{-\frac{(v-bN)^{2}}{2a}} \int_{max(v,V_{R})}^{V_{F}} e^{\frac{(w-bN)^{2}}{2a}} dw, \quad N \in \mathbb{R}^{+},$$
$$\tilde{N}_{\infty} = a \left(\int_{-\infty}^{V_{F}} e^{-\frac{(v-bN)^{2}}{2a}} \int_{max(v,V_{R})}^{V_{F}} e^{\frac{(w-bN)^{2}}{2a}} dw dv \right)^{-1} = \frac{1}{I(N)}$$

This profile is the equilibrium of the linear equation with given N

$$\frac{\partial p}{\partial t}(v,t) + \frac{\partial}{\partial v}\left[(-v+bN)p(v,t)\right] - a\frac{\partial^2 p}{\partial v^2}(v,t) = \delta(v-V_R)N(t)$$

Plateau distributions of simulations coincide with pseudo equilibria, for *N* increasing.



b = 1.5

b = 2.2

Pseudo-equilibria sequences

Pseudo-equilibria sequence

(C-Cañizo-RamosLora, 2024)

• Firing rates sequence: Given $0 \le N_0$

$$N_{0,\infty} := N_0$$
 and $N_{k+1,\infty} := \frac{1}{I(N_{k,\infty})}$ $k = 0, 1, 2, ...$

(Recursive equation $N_{k+1,\infty} = f(N_{k,\infty})$ with $f(x) := \frac{1}{I(x)}$)

Remark: Given p_0 if $N_0 := -a\partial_v p_0(V_F)$ and $N_0 = N_\infty$ then $N_{k,\infty} = N_\infty$

Pseudo-equilibria sequence:

$$p_{k,\infty}(v) = \frac{N_{k+1,\infty}}{a} e^{-\frac{(v-bN_{k,\infty})^2}{2a}} \int_{max(v,V_R)}^{V_F} e^{\frac{(w-bN_{k,\infty})^2}{2a}} dw.$$

These sequences are independent of the Fokker-Planck equation and depend only on b, V_R , V_F

C-Cañizo-RamosLora, Phys. Rev. E 110 (2024)

Pseudo-equilibria sequences b > 0: Monotony of $\{N_{k,\infty}\}_{k \ge 0}$

- If N^* is the only solution of NI(N) = 1 thus:
 - If $N^* \le N_0$ then $\{N_{k,\infty}\}_{k>0}$ is a decreasing sequence which tends to N^*
 - ♦ If $N_0 \le N^*$ then $\{N_{k,\infty}\}_{k>0}$ is a increasing sequence which tends to N^*
- If NI(N) = 1 has not solution then $\{N_{k,\infty}\}_{k>0}$ diverges
- If NI(N) = 1 has two solutions: N_1^* and N_2^* ($N_1^* < N_2^*$), thus:
 - ♦ If $N_0 \le N_1^*$ then $\{N_{k,\infty}\}_{k>0}$ is a increasing sequence which tends to N_1^*
 - ♦ If $N_1^* \le N_0 \le N_2^*$ then $\{N_{k,\infty}\}_{k>0}$ is a decreasing sequence which tends to N_1^*
 - ♦ If $N_2^* \le N_0$ then $\{N_{k,\infty}\}_{k>0}$ diverges



see the precise statement of the theorem in

C-Cañizo-RamosLora, Phys. Rev. E 110 (2024)
Pseudo-equilibria sequences

b < 0: Monotony of $\{N_{k,\infty}\}_{k\geq 0}$

There exists a value of the connectivity parameter b, $b^* < 0$, such that:

- If $b^* < b \le 0$ the sequence $\{N_{k,\infty}\}_{k>0}$ tends to the unique solution of NI(N) = 1
- If $b < b^*$, there exist two values N^- , N^+ , $0 \le N^- < N^+$, such that the sequence $\{N_{k,\infty}\}_{k>0}$ tends to the 2-cycle $\{N^-, N^+\}$



. – p.77/95

For large delay, the NNLIF equation evolves as the pseudo equilibrium sequence

We observe numerically:

- *b* > 0:
 - A unique steady: system tends to it
 - Two steady states: system tends to the steady state with less firing rate or to a plateau distribution
 - Non steady states: system tends to a plateau distribution
- *b* < 0:
 - For b * < b < 0: system tends to the unique steady state
 - For b < b* < 0: system tends to a peridiodic solution (given by the solution initially with a pseudo equilibrium)

Some of these results can be proved analytically (see later slides)

delay=10 b=1.5



delay=25 b=-14



. - p.78/95

delay=25 b=-14



. - p.78/95

Convergence to a steady state

• Entropy method (quasi-linear case)

• New strategy without restrictions on the connectivity parameter

How to overcame |b| small?

Different techniques

(C-Cañizo-RamosLora, 2024, 2025)

Systems with large delay.

Under technical assumptions:

If $\{N_{k,\infty}\} \to N_{\infty}$, thus $\|p(.,t) - p_{\infty}(.)\|_X \le Qe^{-\mu t} \|p_0 - p_{\infty}\|_X$ for all $t \ge 0$, $(Q, \mu > 0)$



Nonlinear system tends through the pseudo-equilibria sequence to p_1 p_2 p_3 p_1 p_2 p_3 d 2d 3d t the limit of the pseudo-equilibria sequence, which is p_{∞}

Only works for weakly connected networks (small |*b*|**)**

Technical difficulties!

Numerical simulations show that this is also true for large b: Global behaviour C-Cañizo-RamosLora, Phys. Rev. E 110 (2024)

Different techniques

(C-Cañizo-RamosLora, 2024, 2025)

Systems with large delay.

Under technical assumptions:

If $\{N_{k,\infty}\} \to N_{\infty}$, thus $\|p(.,t) - p_{\infty}(.)\|_X \le Qe^{-\mu t} \|p_0 - p_{\infty}\|_X$ for all $t \ge 0$, $(Q, \mu > 0)$



Nonlinear system tends through the pseudo-equilibria sequence to p_0 p_1 p_2 p_3 -d 0 d 2d 3d the limit of the pseudo-equilibria sequence, which is p_{∞}

Only works for weakly connected networks (small |*b*|)

Technical difficulties!

Numerical simulations show that this is also true for large *b*: Global behaviour C-Cañizo-RamosLora, Phys. Rev. E 110 (2024)

Local stability through linearization Works for general connectivity strength with and without delay Stability/unstability map in terms of *b* and *d* (at least numerically) Even without any delay some connections with firing rate sequences!! . - p.81/95 C-Cañizo-RamosLora, Commun. Math. Phys. Vol 406, (2025)

Different techniques

(C-Cañizo-RamosLora, 2025)



Value of the stationary firing rate (b > 0) Stability map of the linearized equation, (for b < 0 there is only one equilibrium) stability (dark) or instability (white)

Summary about the simplest NNLIF

- The sign of the connectivity parameter b describes if the network is
 - average-excitatory (b>0)
 - average-inhibitory (b<0)</p>
- Existence of solutions
 - Inhibitory case: Global existence
 - Excitatory case: Local existence
 - Blow-up phenomena
 - If delay transmission is included there is global existence
- Stationary solutions
 - Inhibitory case: A unique steady states
 - Excitatory case:
 - *b* small a unique steady states
 - *b* large non steady states
 - Intermediate values of *b*: at least one or at least two

Summary about the simplest NNLIF

Pseudo equilibria

- Large-delay NNLIF models can be approximated by a discrete sequence of pseudo equilibrium sequence
- Quick simulations give accurate information about the NNLIF system
- Periodic solutions appear for strongly inhibitory systems with large delay
- For excitatory systems with large delay bistability phenomenon appears between the steady state with less firing rate and a plateau distribution

Summary about the simplest NNLIF

Two different methods to prove convergence to equilibrium

- Entropy dissipation method:
 - \diamond |*b*| small is required to control the term without sign
- Strong norm + spectral gap for linear equations
 - New strategy
 - Applied without restriction on b
 - Surprising link with pseudo equilibria
 - Open question Does it work for plateau distributions and periodic solutions (inhibitory case)?
 - It works for other models

Open question How to prove the convergence to periodic solutions? see works of Roux-Salort and collaborators

Extensions of NNLIF

- Refractory state
- Randomness on the discharge potential
- Network consisting of excitatory and inhibitory neurons, as different populations
- Network consisting of excitatory and inhibitory neurons with delay and refractory states
- Nonlinear Fokker-Planck including conductance



- A few mathematical models which describe the activity of neural networks by means of the membrane potential
 - ODE models:
 - Hodgkin-Huxley model
 - Morris-Lecar model
 - FitzHugh-Nagumo model
 - Integrate-and-fire model

Course summary

- A few mathematical models which describe the activity of neural networks by means of the membrane potential
 - ODE models
 - PDE models:
 - Nonlinear Noisy Leaky Integrate and Fire (NNLIF): $\rho(t, v), \rho_E(t, v), \rho_I(t, v), R_E(t), R_I(t)$
 - Nonlinear Fokker-Planck including conductance: $\rho(t, v, g)$
 - Age-structured partial differential equations $\rho(t,s)$

$$\begin{cases} \partial_t \rho(t, a) + \partial_a \rho(t, a) + S(a, X(t))\rho(t, a) = 0\\ \rho(t, a = 0) = N(t) \coloneqq \int_0^\infty S(a, X(t))\rho(t, a) \, da \quad t > 0,\\ \rho(t = 0, a) = \rho^0(a) \qquad \qquad a > 0, \end{cases}$$

- Different past network activity:
 - $\cdot \quad X(t) = JN(t)$
 - $\cdot \quad X(t) = JN(t-d)$
 - $X(t) = \int_0^\infty \alpha(s)N(t-s) \, ds$ with $\int_0^\infty \alpha(s) \, ds = 1$ and $\alpha(\cdot) \ge 0$
- $J \ge 0$ is the strength of interconnections



- A few mathematical models which describe the activity of neural networks by means of the membrane potential
 - ◊ ODE models
 - PDE models
- Results related with neurophysiological phenomena
- Math issues:
 - Steady states
 - Local/global existence Blow-up phenomenon
 - Long time behaviour

Thank you very much for your attention

(and for using your neurons for it!)

We keep in touch (caceres@ugr.es)

. – p.88/95

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies

$$\frac{d}{dt} \int_{-\infty}^{V_F} \phi(v) p(v,t) \, dv \ge \mu \int_{-\infty}^{V_F} (bN(t) - v) \phi(v) p(v,t) \, dv$$

$$+\mu^2 a_m \int_{-\infty}^{V_F} \phi(v) p(v,t) \, dv + N(t) \left(\phi(V_R) - \phi(V_F) \right)$$

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies

$$\frac{d}{dt} \int_{-\infty}^{V_F} \phi(v) p(v,t) \, dv \ge \mu [bN(t) + \underbrace{\mu a_m - V_F}_{>0}] \int_{-\infty}^{V_F} \phi(v) p(v,t) \, dv$$

 $-N(t)\phi(V_F)$

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies



 $-N(t)\phi(V_F)$

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies

$$\frac{d}{dt}M_{\mu}(t) \ge \mu[bN(t) + \mu a_m - V_F]M_{\mu}(t)$$
$$-N(t)\phi(V_F)$$

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies

$$\frac{a}{dt}M_{\mu}(t) \ge \mu[bN(t) + \mu a_m - V_F]M_{\mu}(t)$$
$$-N(t)\phi(V_F)$$

and by Gronwall's lemma:

$$M_{\mu}(t) \ge e^{\mu \int_{0}^{t} (bN(s) + \mu a_{m} - V_{F}) \, ds} \left(M_{\mu}(0) - \phi(V_{F}) \int_{0}^{t} N(s) e^{-\mu \int_{0}^{s} (bN(z) + \mu a_{m} - V_{F}) \, dz} \, ds \right)$$

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies

$$\frac{a}{dt}M_{\mu}(t) \ge \mu[bN(t) + \mu a_m - V_F]M_{\mu}(t)$$
$$-N(t)\phi(V_F)$$

and by Gronwall's lemma:

$$M_{\mu}(t) \ge e^{\mu \int_0^t (bN(s) + \mu a_m - V_F) ds} \left(M_{\mu}(0) - \frac{\phi(V_F)}{\mu b} \right)$$

We choose $\phi(v) = e^{\mu v}$ with $\mu > \max(\frac{V_F}{a_m}, \frac{1}{b})$, then a weak solution satisfies

$$\begin{split} M_{\mu}(t) &\geq K e^{\mu(\mu a_m - V_F)t} \text{ with } \mu(\mu a_m - V_F) > 0\\ \text{and } K > 0 \text{ is we assume the initial data such that}\\ K &:= \left(M_{\mu}(0) - \frac{\phi(V_F)}{\mu b} \right) > 0 \end{split}$$

But since p(v, t) is a probability density, $\int_{-\infty}^{V_F} p(v, t) dv = \int_{-\infty}^{V_F} p^0(v) dv = 1, \text{ and } \mu > 0 \text{ then}$

$$M_{\mu}(t) = \int_{-\infty}^{V_F} \phi(v) p(v,t) \, dv \leq e^{\mu V_F},$$

leading to a contradiction

Notion of solution

A pair of nonnegative functions (p, N) with $p \in L^{\infty}(\mathbb{R}^+; L^1_+(-\infty, V_F)), N \in L^1_{loc,+}(\mathbb{R}^+)$ is a weak solution if for any test function $\phi(v, t) \in C^{\infty}((-\infty, V_F] \times [0, T])$ such that $\frac{\partial^2 \phi}{\partial v^2}$, $v \frac{\partial \phi}{\partial v} \in L^{\infty}((-\infty, V_F) \times (0, T))$, we have

$$\int_0^T \int_{-\infty}^{V_F} p(v,t) \left[-\frac{\partial \phi}{\partial t} - \frac{\partial \phi}{\partial v} h(v,N) - a \frac{\partial^2 \phi}{\partial v^2} \right] dv \, dt =$$

$$\int_0^T N(t) [\phi(V_R, t) - \phi(V_F, t)] dt +$$
$$\int_{-\infty}^{V_F} p^0(v) \phi(0, v) dv - \int_{-\infty}^{V_F} p(v, T) \phi(T, v) dv.$$

Notion of solution

• By choosing test functions: $\psi(t)\phi(v)$ where $\phi(v) \in C^{\infty}((-\infty, V_F]), v \frac{\partial \phi}{\partial v}, \frac{\partial^2 \phi}{\partial v^2} \in L^{\infty}((-\infty, V_F)),$

$$\frac{d}{dt} \int_{-\infty}^{V_F} \phi(v) p(v,t) dv = \int_{-\infty}^{V_F} \left[\frac{\partial \phi}{\partial v} h(v,N) + a \frac{\partial^2 \phi}{\partial v^2} \right] p(v,t) dv$$

 $+N(t)[\phi(V_R)-\phi(V_F)]$

holds in the distributional sense

•
$$\phi \equiv 1 \Longrightarrow \int_{-\infty}^{V_F} p(v,t) dv = \int_{-\infty}^{V_F} p^0(v) dv = 1$$

Rewriting as a Stefan like problem

(Rescale the variables, in order to have a = 1 and $V_F = 0$)

First change of variables: (Classical change to transform the linear Fokker-Planck into a heat equation, see *Carrillo-Toscani, Ind. Univ. Math. Jour. (2000)*)

$$y = e^t v, \quad \tau = \frac{1}{2}(e^{2t} - 1)$$

Define

$$w(y,\tau) = \alpha(\tau)p(y\alpha(\tau), -\log(\alpha(\tau)))$$

and $M(\tau) = N(t)\alpha^2(\tau)$ where $\alpha(\tau) = (\sqrt{2\tau + 1})^{-1}$

firing rate in new variables

Second change of variables:

$$x = y - \int_0^\tau \mu(t - d)\alpha(s) \, ds \quad \mu(t) := b_0 + bN(t)$$

Define $u(x, \tau) = w\left(x + \int_0^{\tau} \mu(t - d)\alpha(s) \, ds, \tau\right)$

Carrillo-González-Gualdani-Schonbek, Comm. in PDEs, Vol. 38(3), 385-409, (2013) for d = 0

Rewriting as a Stefan like problem

Thus we obtain for $\tau > 0$, $x < s(\tau)$:

$$\begin{cases} u_t(x,\tau) = u_{xx}(x,\tau) + M(t)\delta(x - s_1(\tau)), \\ s_1(\tau) = s(\tau) + \frac{V_R}{\alpha(\tau)}, \\ s(\tau) = -b_0(\sqrt{2\tau + 1} - 1) - b \int_0^{\tau} N(t - d)\alpha(s)ds, \\ M(\tau) = -u_x(s(\tau), \tau), \\ N(t) = N(0), \quad t \in (-d, 0], \\ u(-\infty, \tau) = u(s(\tau), \tau) = 0, \\ u(x, 0) = u_0(x), \quad x < 0, \end{cases}$$

where d > 0 and $\alpha(\tau) = \frac{1}{\sqrt{2\tau+1}}$

Rewriting as a Stefan like problem

Handling the delay we obtain the equivalent system

$$\begin{array}{l} (u_t(x,t) = u_{xx}(x,t) + M(t)\delta(x - s_1(t)), \\ s_1(t) = s(t) + \frac{V_R}{\alpha(t)}, \\ s(t) = -b_0(\sqrt{2t+1}-1) - \frac{b}{\sqrt{1-\hat{d}}} \int_{-\frac{1}{2}\hat{d}}^{(1-\hat{d})t - \frac{1}{2}\hat{d}} M(s)\alpha^{-1}(s)ds, \\ M(t) = -u_x(s(t),t), \\ M(t) = M(0), \\ t \in (-\hat{d},0], \\ u(-\infty,t) = u(s(t),t) = 0, \\ u(x,0) = u_0(x), \\ x < 0, \end{array}$$

where $\hat{d} = (1 - e^{-2d}) \in [0, 1)$ and $\alpha(t) = \frac{1}{\sqrt{2t+1}}$. (return)

Integral formulation

$$M(t) = -2 \int_{-\infty}^{0} G(s(t), t, \xi, 0) u'_{0}(\xi) d\xi$$

$$+2\int_0^t M(\tau)G_x(s(t),t,s(\tau),\tau)d\tau - 2\int_0^t M(\tau)G_x(s(t),t,s_1(\tau),\tau)d\tau,$$

where *G* is the Green's function for the heat equation on the real line $G(x, t, \xi, \tau) = \frac{1}{\sqrt{4\pi(t-\tau)}} e^{-\frac{|x-\xi|^2}{4(t-\tau)}}$ and satisfies the Green identity

$$\frac{\partial}{\partial\xi} \left(G \frac{\partial u}{\partial\xi} - u \frac{\partial G}{\partial\xi} \right) - \frac{\partial}{\partial\tau} (Gu) = 0$$

Local existence

With a fixed point argument and the integral formulation of M:

Theorem (C-Roux-Salort-Schneider) [Local existence] Let $u_0(x)$ be a non-negative function in

 $C^{0}((-\infty, 0]) \cap C^{1}((-\infty, V_{R}) \cup (V_{R}, 0]) \cap L^{1}((-\infty, 0))$ such that $u_{0}(0) = 0$.

Suppose u_0 , $(u_0)_x$ decay to zero as $x \to -\infty$ and that the left and right derivatives at V_R are finite.

Then there exists a time T > 0 such that M(t) defined by the integral formulation exists for $t \in [0, T]$ and is unique in $C^0([0, T])$. The existence time T satisfies

$$T \leq \left(\sup_{x \in (-\infty, V_R) \cup (V_R, 0]} |u'_0(x)|\right)^{-1}.$$

Local existence

And as a corollary

There exists a unique solution of the Stefan like problem for $t \in [0, T]$

Proof. Once M is known the equation for u decouples, and u can be calculated via the Duhamel's formula

$$\begin{split} u(x,t) &= \int_{-\infty}^{V_R} G(x,t,\xi,0) u_0(\xi) \, d\xi + \int_{V_R}^0 G(x,t,\xi,0) u_0(\xi) \, d\xi \\ &- \int_0^t M(\tau) G(x,t,s(\tau)\tau) \, d\tau + \int_0^t M(\tau) G(x,t,s_1(\tau)\tau) \, d\tau. \end{split}$$

Finally, the local existence theorem is translated into the NNLIF equation, since ρ and N are recovered undoing the changes of variables

Super solution

Let $T \in \mathbb{R}_+$, $d \ge 0$ ($\bar{\rho}, \bar{N}$) is said to be a (classical) super solution to the delayed NNLIF model on $(-\infty, V_F] \times [0, T]$ if for all $t \in [0, T]$ we have $\bar{\rho}(V_F, t) = 0$ and

 $\partial_t \bar{\rho} + \partial_v [(-v + b\bar{N}(t - d))\bar{\rho}] - a \partial_{vv} \bar{\rho} \ge \delta_{v = V_R} \bar{N}(t),$

 $\bar{N}(t)=-a\partial_v\bar{\rho}(V_F,t),$

on $(-\infty, V_F] \times [0, T]$ in the distributional sense and on $((-\infty, V_F] \setminus V_R) \times [0, T]$ in the classical sense, with arbitrary values for \overline{N} on [-d, 0)
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We consider super solution $\bar{\rho}$ on [0, d] of the form

 $\bar{\rho}(v,t) = e^{\xi t} f(v),$

where ξ is large enough and f is a carefully selected function.

Super solution

Comparison principle

Let (p, N) be a solution of the NNLIF model on $(-\infty, V_F] \times [0, T]$ for the initial condition (p_0, N_0) and (\bar{p}, \bar{N}) be a super-solution $(-\infty, V_F] \times [0, T]$. Assume that $\forall v \in (-\infty, V_F]$, $\bar{p}(v, 0) \ge p_0(v)$ and $\forall t \in [-d, 0)$, $\bar{N}(t) = N_0(t)$. Then

 $\forall (v,t) \in (-\infty, V_F] \times [0,T], \ \bar{p}(v,t) \ge p(v,t) \text{ and } \bar{N}(t) \ge N(t)$

And we find a contradiction if we assume that the firing rate explodes in a finite time

(return)